



A Photovoltaic based DC/AC Single-Phase Pure Sine wave Inverter

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Abstract: Solar photovoltaic energy is a booming industry in power generation sector. The DC-AC power converter plays a major role in photovoltaic conversion independent of PV module topology. In this paper, a single phase full bridge converter along with H-bridge inverter is simulated using MATLAB/Simulink. An intermediary High-frequency step-up transformer is used to step up the low voltage PV panel output to the mains AC supply voltage. The circuit has a total harmonic distortion below 5% at steady state. Perturb and Observe MPPT is used at the full bridge converter side to control the duty cycle and Sinusoidal Pulse Width Modulation is used to control the switching at H-Bridge inverter side. The distortion at the output side is minimized by employing a suitable filter to attain better performance of the inverter.

Keywords: Solar Photovoltaic (PV); Full-Bridge DC-DC Converter; High-Frequency step-up transformer; Single-Phase H-Bridge pure sine-wave inverter; Sinusoidal Pulse Width Modulation (SPWM); Power Electronics.

I. INTRODUCTION

Solar PV based energy is gaining popularity because of its simplicity, availability and relatively low maintenance. Solar PV systems can meet large energy requirements at low cost with proper design and implementation in places where a lot of sunlight is received.

Both the converter and inverter circuits play a major role in PV power conversion systems. Usually, the general topology for a PV based power conversion system is a boost converter followed by an H-Bridge inverter [1]. PV converters are classified into Grid connected and Standalone power generation systems [2]. The main objective here is to build a standalone inverter while providing pure sine wave output and reduced harmonic distortion.

the output of the inverter in order to reduce harmonic distortions. Perturb and Observe MPPT Technique [4] is used to extract the maximum possible power from panel output thus improving the overall efficiency of the system.

II. SYSTEM DETAILS

A. Photovoltaic panel

A PV cell is the smallest unit which transforms solar energy into electrical energy. Group of PV cells forms a module or a panel. Cells are connected in series and parallel combinations within the module to obtain panel rated voltage and current.

Modules can be connected in series or parallel combination to obtain required current and voltage. Thus connected modules are called as Strings. In order to generate several kilowatts of energy, there may be hundreds or thousands of Strings within a solar power generating station.

A Solar PV panel always produces DC power at the output. Various mathematical modeling exists to describe the PV panel equivalent circuit [5]. The current output of the panel depends on Solar Irradiation and temperature. The current-voltage relationship (I-V Curve) and the power-voltage relationship (P-V curve) play a key role in determining the PV panel characteristics and the power output of the panel. Both are non-linear curves and vary with the temperature and irradiation. Fig 3 shows the PV Panel characteristics for different values of Irradiations.

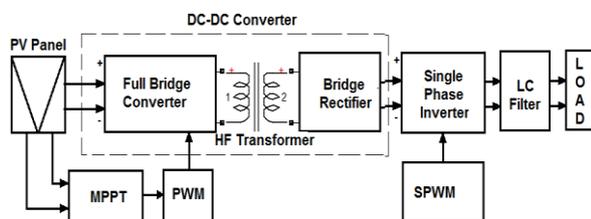


Fig 1: Block diagram of Photovoltaic Inverter with Full bridge converter

Fig 1 shows the block diagram of the proposed system. The system consists of a Full Bridge DC to DC Converter, High-frequency step-up transformer, and an H-Bridge Inverter. The inverter is controlled by unipolar SPWM technique [3]. A passive low pass LC Filter is connected to

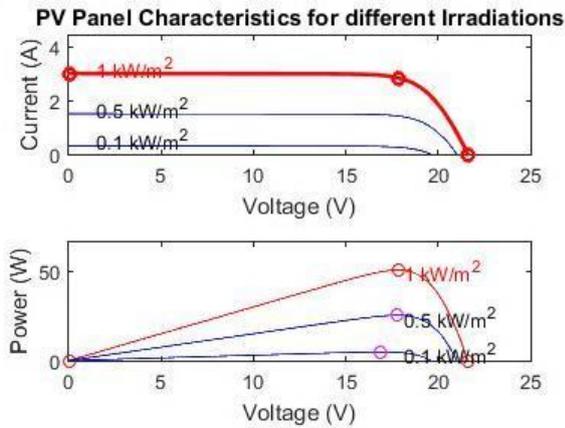


Fig 3: PV Panel Characteristics for different Irradiations

B. Perturb and Observe Algorithm

In order to obtain the maximum power output from the module, various MPPT Algorithms can be implemented. Because of its simplicity, P&O is the most commonly and widely used MPPT algorithm. The P&O algorithm is called as the hill climbing algorithm because the curve is rising ($dP/dV > 0$) on the left and the falling ($dP/dV < 0$) on the right side of the P-V characteristics.

The P&O Algorithm involves the process of modifying the output voltage of the DC link between the array and the converter by perturbing the duty cycle. The sign of the last perturbation and the corresponding change in power is used to decide the next perturbation.

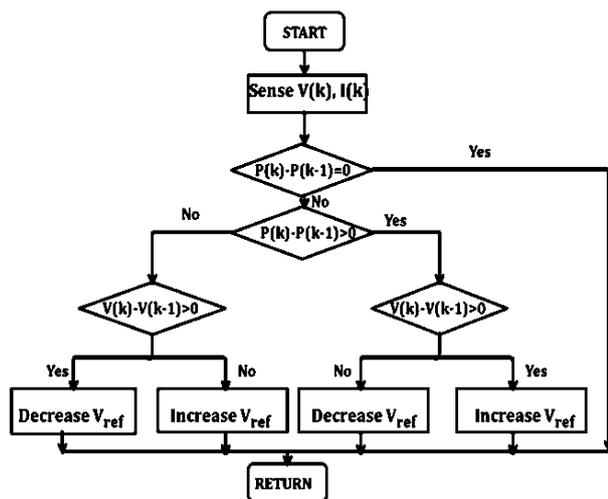


Fig 4: Perturb and Observe Algorithm

If the output power of the PV Panel increases, the next perturbation is kept in the same direction. If the perturbation causes a reduction in power, then the sign next perturbation will be opposite. Based on these facts, the algorithm is implemented as shown in the flowchart in Fig.4. This process is repeated until the peak power point is

reached. The operating point always oscillates around the MPP.

C. DC-DC Converter

The DC to DC Converter in this circuit consists of a full bridge converter, a High-frequency step-up transformer, and a diode bridge. A full bridge converter consists of four MOSFET switches as shown in fig 5. These switches are controlled by PWM pulses. The P&O MPPT determines the value of duty ratio. The Full bridge converter converts the continuous DC output voltage of the PV Panel into pulses of high frequency (40 kHz) by the switching action of the MOSFET switches. The high-frequency switching reduces the overall size and weight of the transformer. The primary winding (LV) of the High-frequency step-up transformer is connected to the full bridge converter.

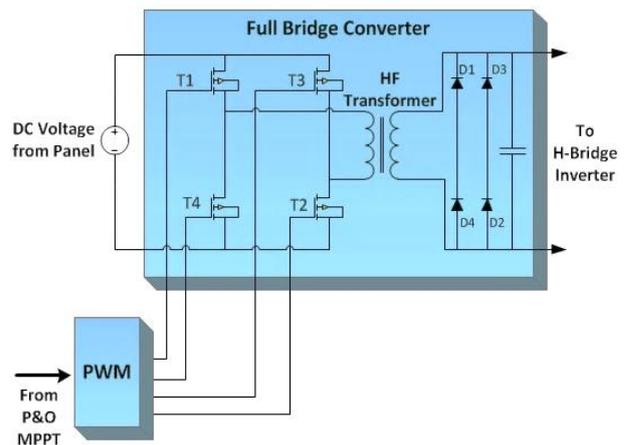


Fig 5: Full Bridge converter

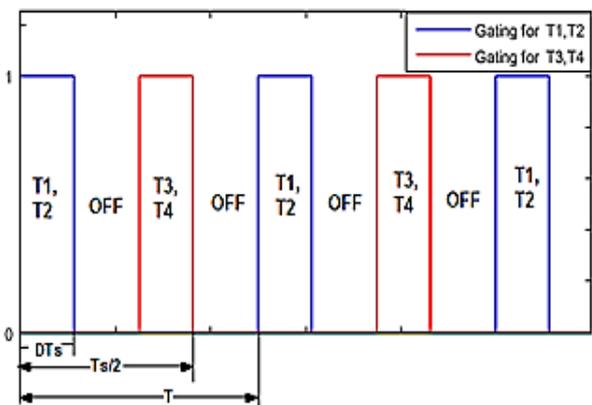


Fig 6: PWM Gating Pulses for Full Bridge converter

The gating pulses to the full bridge converter are as shown in fig 6. The total switching time is T. At interval 0 to DTs, the switches T1 and T2 are turned on. The current through the transformer primary is positive hence positive voltage is produced at the secondary. A zero signal is followed after the interval DTs during which all the



switches are off. After the zero signal interval, switches T3 and T4 are turned on up to interval $T_s/2$. During this interval, the current through the transformer primary is negative as a result negative output voltage is produced at the secondary. Again, a zero signal is followed after the interval $T_s/2$ to T during which all the switches are off.

The diode bridge is connected across the secondary winding of the High-frequency step-up transformer. It consists of four diodes and converts the stepped-up AC voltage pulses into smooth DC Voltage. Full wave diode bridges have better performance and low voltage stress per component compared to half wave bridge rectifiers. A filter capacitor is usually connected in parallel with the Diode Bridge to reduce the output ripple.

D. H-Bridge Inverter

H-Bridge inverter consists of four MOSFET switches which are connected in ‘‘H’’ shape to form a bridge. These switches are used to control the direction of current running from the DC source to the connected load in either direction. Hence it converts the input DC power into AC output power. The MOSFETs are switched from an SPWM generating circuit to get nearly sine wave AC output. The switching frequency of the switches is equal to the mains AC supply frequency (50 Hz in this case).

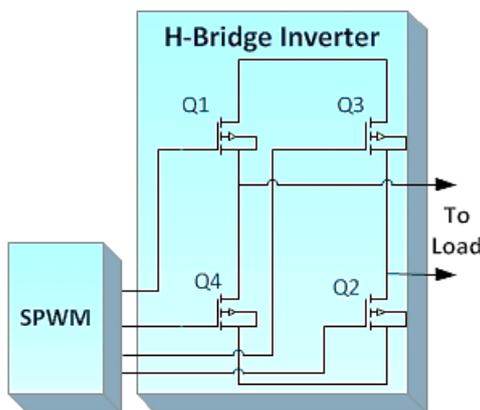


Fig 7: H-Bridge Inverter with SPWM control

E. Sinusoidal Pulse Width Modulation

In this simulation, SPWM is used to generate sine wave output from DC input. SPWM technique is characterized by constant amplitude pulse with varying duty cycle for each period. To generate SPWM signals, a high-frequency triangular wave is used as carrier signal (V_t), which is compared with sinusoidal waves ($V_{\sin(x)}$ and $V_{\sin(180+x)}$) which are 180° out of phase with each other. The resulted signal is called the reference signal (V_r). This signal is then provided to the switches of the H-Bridge inverter. Here unipolar SPWM technique is used.

The most important parameter of designing the switching strategy is amplitude modulation (M_A) that will influence the performance of the inverter. M_A is defined as the ratio

of the magnitudes between sine waveform (reference signal) and the triangular waveform (carrier signal). The amplitude modulation is determined by the following equation:

$$M_A = \frac{V_r}{V_c}$$

Usually, the value of M_A is chosen between 0.8 and 0.9. If M_A is greater than 1, there will be more harmonics at the output. This condition is known as over modulation and should be avoided. Fig 8 illustrates the unipolar SPWM Technique.

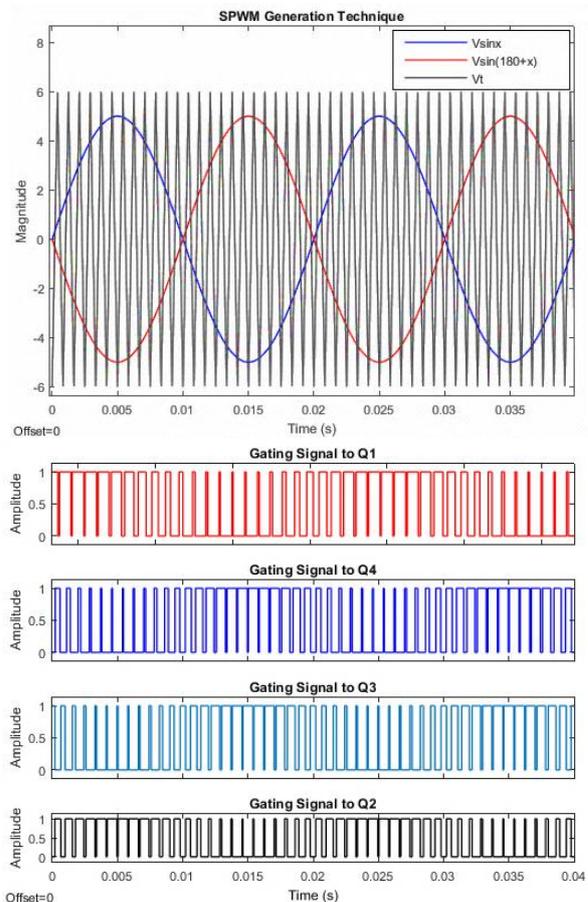


Fig 8: SPWM generating technique gating pulses to H-Bridge Inverter

F. Filter Circuit

The filter circuit in this inverter consists of an LC circuit which reduces the output harmonics thus reducing THD. Since SPWM technique is used, the filtering requirement is fairly less. The filter inductor (L_f) and the filter capacitor (C_f) are designed so that the cut-off frequency (f_c) is 75Hz which is greater than 50Hz but much less than harmonic frequency. The L_f and C_f Values are determined by the formula:

$$f_c = \frac{1}{2\pi\sqrt{L_f C_f}}$$

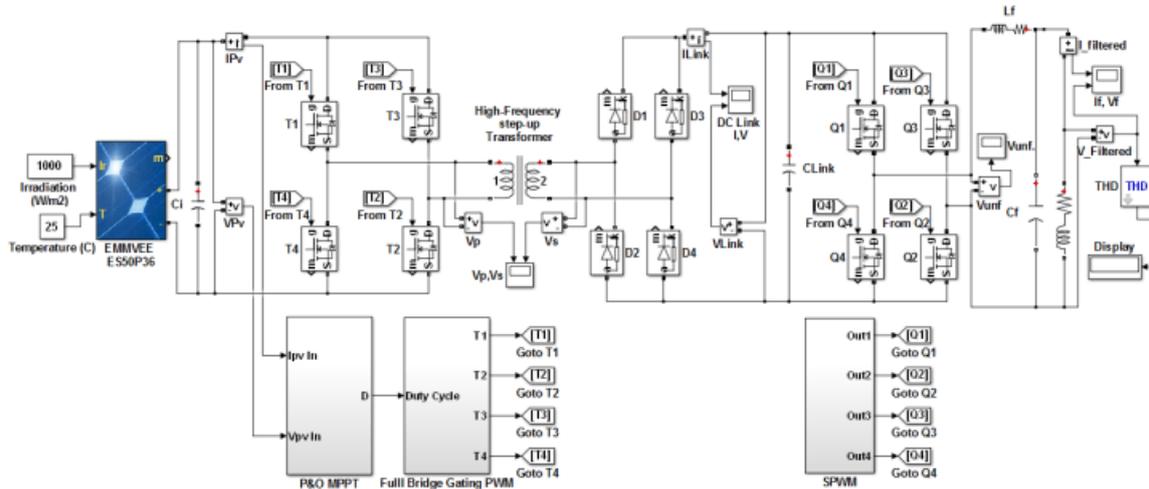


Fig 9: MATLAB Model of Single phase PV inverter with Full Bridge converter

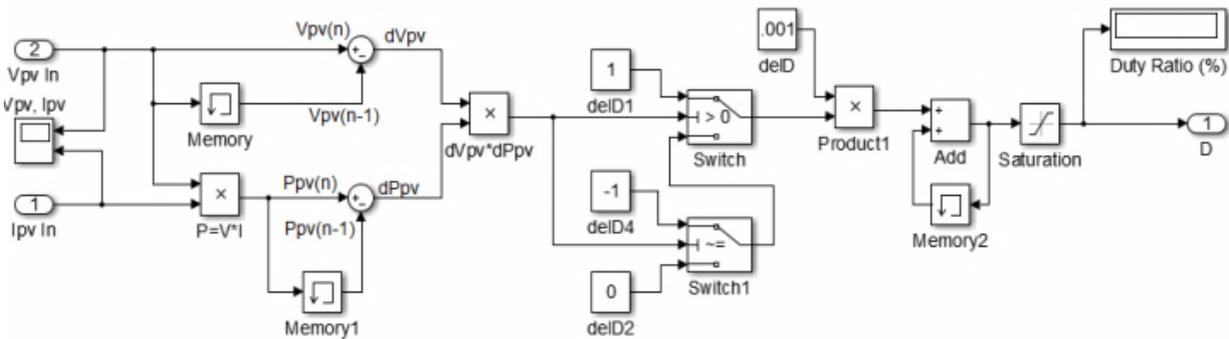


Fig 10: Perturb and Observe MPPT Implementation in MATLAB/Simulink

III. SIMULATION STUDIES

The single-phase H-bridge inverter is simulated using MATLAB/Simulink software. Fig. 9 shows the schematic diagram of Single-phase PV inverter with Full Bridge converter system implementation in MATLAB. The transformer and the PV panel data is directly entered to the simulator.

The gating signals which are obtained from PWM and SPWM techniques are applied to the Full Bridge converter and H-Bridge inverter respectively. The output of the inverter contains harmonics which is filtered by the LC filter circuit. Thus a pure sinusoidal voltage waveform is produced at the output.

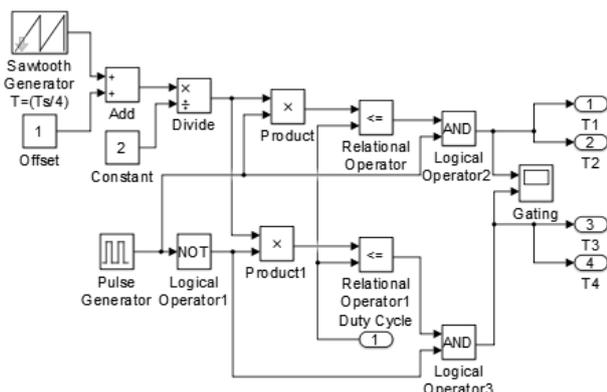


Fig 11: Calculation of duty cycle from P&O MPPT

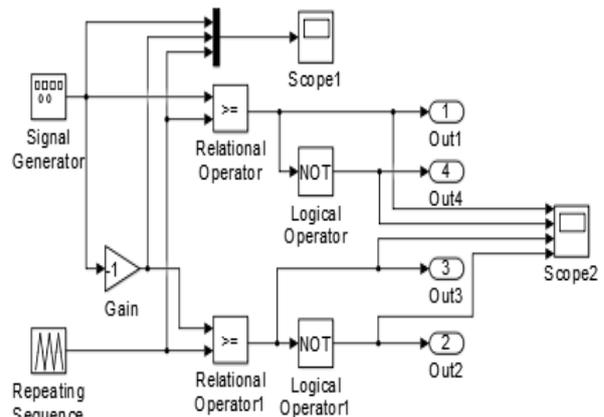


Fig 12 SPWM Subsystem



IV. WAVEFORMS

The Circuit is simulated in the MATLAB/Simulink Software and the output is obtained. Fig 13 shows the current drawn from the PV Panel and the voltage across the PV Panel. The voltage across primary and secondary windings of the transformer is as shown in fig 14. The DC link voltage and current in between the converter and inverter are shown in fig 15. Fig 16 shows unfiltered output voltage and fig 17 shows the filtered voltage and current at the output load side of the inverter.

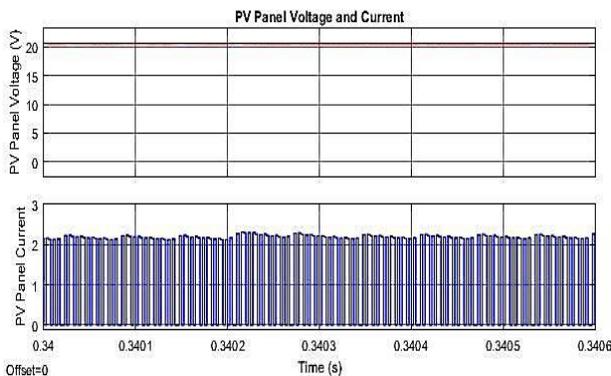


Fig 13: PV Panel Voltage and Current

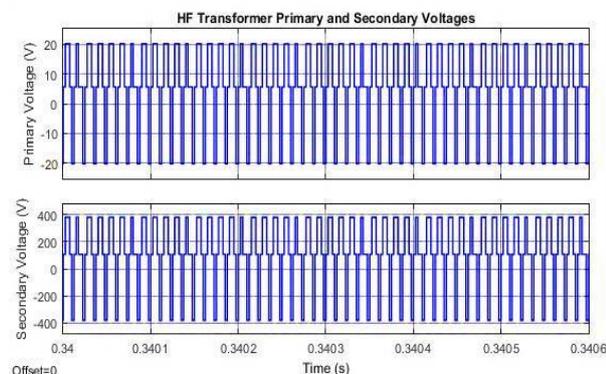


Fig 14: Primary and Secondary Voltages of HF step-up Transformer

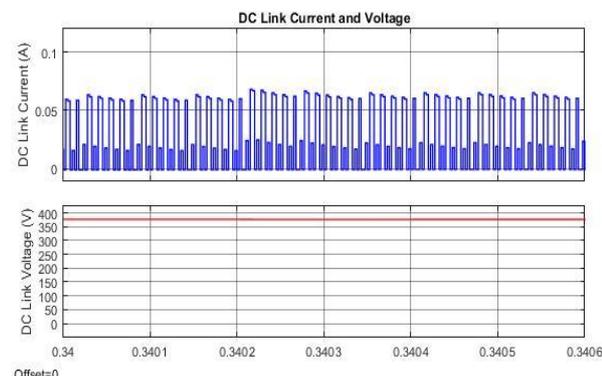


Fig 15: DC link voltage and current in between the converter

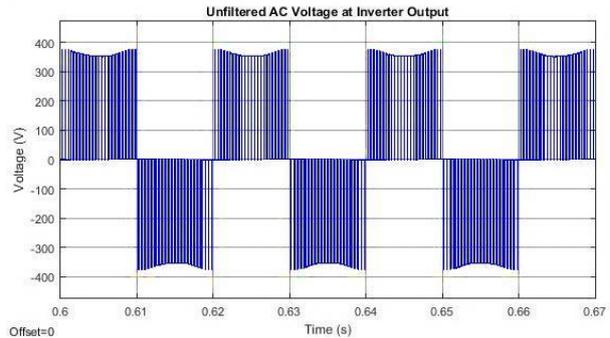


Fig 16: Unfiltered AC Voltage at Inverter Output

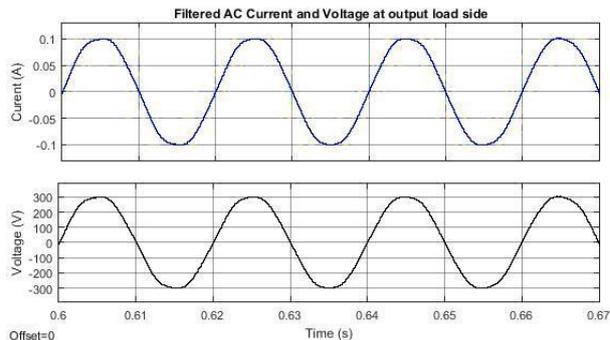


Fig 17: Unfiltered AC Voltage at Inverter Output

V. CONCLUSION

This paper presents the design and simulation of a pure sine wave inverter for photovoltaic applications. Various advantages exist in the proposed system such as low switching loss, high efficiency, low cost, galvanic isolation between converter and inverter side and small size.

Simulation of this inverter shows that power from PV array can be converted to the pure sine wave output voltage and the fundamental harmonic component lies at 50 Hz and higher harmonic components are completely eliminated. Thus it can be concluded that this sine wave inverter is ideal for the photovoltaic power systems.

ACKNOWLEDGMENT

I would like to express my sincere gratitude and thanks to **Dr. Nagesh Prabhu**, HOD, Electrical and Electronics Engineering Dept., Nitte and my project Guide, Ms. Swathi Hatwar, Asst. Professor of Electrical and Electronics Engineering, for all the guidance, encouragement and support.

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**International Journal of Innovative Research in
Electrical, Electronics, Instrumentation and Control Engineering**



NCAEE 2017

National Conference on Advances in Electrical Engineering

NMAM Institute of Technology, Nitte

Vol. 5, Special Issue 2, April 2017

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